Cood No.	Emmalmant No
Seat No.:	Enrolment No.

GUJARAT TECHNOLOGICAL UNIVERSITY BE SEM-V Examination-Nov/Dec.-2011

Subject code: 151704 Date: 03/12/2011 **Subject Name: Industrial Control Systems** Time: 2.30 pm -5.00 pm Total marks: 70 Instructions: 1. Attempt all questions. 2. Make suitable assumptions wherever necessary. 3. Figures to the right indicate full marks. 0.1 (a) Draw cascade control scheme for any one application. Discuss the 07 advantages of cascade control configuration. With neat sketch explain DDC in detail. Discuss the benefits of DDC. 07 (a) Discuss various control valve characteristics compare the sensitivities of 07 **Q.2** the three valve characteristics. **(b)** Draw a hierarchical DCS structure and explain the function of each level. **07** OR With necessary sketch explain the three main components of SCADA. 07 0.3 Compare the followings. 07 Open loop Control & Closed loop Control (i) Feed forward Control & Feed back Control (I) Differentiate between distributed and lumped parameter **(b)** 04 System with the help of an example. (II) Compare two-position and multi position mode, 03 OR Discus Process Reaction Curve Method for Controller Tuning. 07 Q.3 (a) **(b)** 04 (I) Design a proportional -integral controller with a proportional band of 30 % and an integration time of 10 seconds. The 4-20 mA input converts into 0-2 V error signal. The output is to be in between 0-10 V. Design a 1:4 Demultiplexer using PLC ladder diagram. (II)03 0.4 (a) (I) List the advantages of PLC over relay based logic. 04 (II) Define static error, offset and velocity error. 03

	(b)	Consider the error Voltage E_p is given by the following relation:	
		$E_p = t\% \qquad (0-1 \text{ sec })$	
		$E_p = 1\%$ (1-3 sec)	
		$E_p = 1\%$ (1-3 sec) $E_p = (-1/2) t + 2.5\%$ (3-5 sec)	
		Find the controller output for a three mode controller which produces an output with $K_p = 5$, $K_i = 0.5 \text{ sec}^{-1}$, $K_d = 0.5 \text{ s}$ and $P_0 = 20\%$.	
		OR	
Q.4	(a)	Explain the cavitation and flashing phenomena in control valve with the help of a diagram.	
Q.4	(b)	Explain the role of Functional Identification and loop Identification In P & I Diagrams.	07
Q.5 (a)	(a)	With Necessary sketches explain Various configurations of ratio control.	07
	(b)	Discuss proportional control mode in detail. What is the drawback of proportional control mode? How it can be eliminated?	07
		OR	
Q.5	(a)	With neat sketch discuss globe valve in detail.	07
	(b)	Discuss "Integral windup and Anti-windup"	07
