Seat No.:	Enrolment No.

Subject Code: 162003

GUJARAT TECHNOLOGICAL UNIVERSITY

BE - SEMESTER-VI • EXAMINATION - SUMMER 2013

Date: 28-05-2013

Tiı	ne: 1 cructio 1.	Attempt all questions.	
		Make suitable assumptions wherever necessary. Figures to the right indicate full marks.	
Q.1	(a)	State essential parts of electrical drives. What are the functions of power modulator, control unit, sensor unit?	07
Q.2	(b) (a)	Explain the advantage of electrical drives as compared to other prime movers. Explain the Multi quadrant operation of electrical drives with suitable	07 07
Q	(b)	conventions and example. Derive the Equivalent values of drive parameter. OR	07
	(b)	Describe the component of load torque and classification of load torque.	07
Q.3	(a)	A drive has following parameters: J=10 kg-m², T=100-0.1N, N-m, Passive load torque Tl=0.05N, N-m.Initially the drive is operating in steady state. Now it is to be reversed. For this motor	07
	(b)	chara. T is changed to T= - 100-0.1N, N-m.Calculate the time of reversal. Derive the Fundamental motor torque and motor-load dynamic system equation.	07
Q.3	(a)	OR Explain the single phase fully wave controlled converter with R-L-E load with	07
	(b)	necessary waveform and conduction table. Explain the Chopper circuit principle, operation and its classification.	07
Q.4	(a)	Explain the control strategy of chopper circuit with pulse width modulation and	07
	(b)	state its advantage and disadvantage. Explain the Type A & Type B chopper circuit. OR	07
Q.4	(a)	Derive the steady state analysis of step up chopper with Min. and Max value of	07
	(b)	current. Explain the three phase fully wave controlled converter with R-L-E load with necessary waveform and conduction table.	07
Q.5	(a) (b)	Explain the Universal motor construction, operation and control strategy. Describe the operation of a variable reluctance motor stepper motor. What is micro stepping?	07 07
Q.5	(a) (b)	OR Explain the speed control of single phase induction motor. Deduce the expression for armature current and speed during transient analysis of separately excited motor with Armature control.	07 07
