Seat No.:	Enrolment No.
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## **GUJARAT TECHNOLOGICAL UNIVERSITY**

BE - SEMESTER-VI • EXAMINATION – SUMMER 2013

	Code: 163405 Date: 30-05-2013	
bject	Name: Mechatronics	
2.	Make suitable assumptions wherever necessary.	
(a) (b)	Explain basic elements of a closed loop system.  Explain Linear variable differential transducer in details.	07 07
(a) (b)	Explain different types of stepper motors and its specification.  Explain solid-state devices, which can be used electronically to switch circuit.  OR	07 07
<b>(b)</b>	Explain mechanical factors or aspects for motor selection.	07
(a) (b)	Explain Hydraulic mechanical system as a system model.  Explain Proportional control mode in details with diagram.  OR	07 07
(a) (b)	Explain Derivative control mode in details with diagram. Explain Adaptive control and its commonly used forms.	07 07
(a) (b)	Explain Basic PLC structure in details with figure.  Explain different logic gate function with figure used in PLC.  OR	07 07
(a) (b)	Explain Input/output processing in PLC. Explain Master and Jump controls in PLC.	07 07
(a) (b)	Explain Pick & Place robot system design in details.  Explain Car Engine Management system.  OR	07 07
(a) (b)	Explain Hard Disk Drive case study.  Write short note on Car Park Barriers case study	07 07
	(a) (b) (b) (b) (b) (b) (b) (b) (b) (b) (b	tructions:  1. Attempt all questions. 2. Make suitable assumptions wherever necessary. 3. Figures to the right indicate full marks.  (a) Explain basic elements of a closed loop system. (b) Explain Linear variable differential transducer in details.  (a) Explain different types of stepper motors and its specification. (b) Explain solid-state devices, which can be used electronically to switch circuit.  OR (b) Explain mechanical factors or aspects for motor selection.  (a) Explain Hydraulic mechanical system as a system model. (b) Explain Proportional control mode in details with diagram.  OR (a) Explain Derivative control mode in details with diagram.  (b) Explain Adaptive control and its commonly used forms.  (a) Explain Basic PLC structure in details with figure. (b) Explain different logic gate function with figure used in PLC.  OR (a) Explain Input/output processing in PLC. (b) Explain Master and Jump controls in PLC. (c) Explain Pick & Place robot system design in details. (b) Explain Car Engine Management system.  OR (a) Explain Hard Disk Drive case study.

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