

GUJARAT TECHNOLOGICAL UNIVERSITY**ME Semester –II Examination Dec. - 2011****Subject code: 1720703****Date: 14/12/2011****Subject Name: Power System Dynamics & Control (Power Group)****Time: 02.30 pm – 05.00 pm****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.

- Q.1** (a) State basic assumptions made in steady state analysis of an alternator and derive open circuit voltage equation of it. **07**
(b) Draw the functional block diagram of a typical excitation control system and explain function of each block. **07**

- Q.2** (a) Explain line modeling by D-Q transformation using α - β variables. **07**
(b) Using Park transformation derive voltage equation of synchronous machine. Also state importance of Park transformation. **07**

OR

- (b) Prove that, if the armature flux linkages components, with respect to a synchronously rotating reference frame are constants, then the transformer emf terms and terms introduced by the variations in rotor speed cancel each other. **07**

- Q.3** (a) Draw and explain speed-governing system and model of speed-governing system for steam turbines. **08**
(b) Write short-note on Hopf Bifurcation. **06**

OR

- Q.3** (a) State the types of SVCs. Explain FC-TCR by neat sketch. Also draw block diagram of SVC Controller. **08**
(b) Derive steady state equation of transmission line using phasor notation $f=fQ+jfD$, Draw phasor diagram showing relationship between DQ and dq variables. **06**

- Q.4** (a) Classify load models. Explain static load representation in details. **07**
(b) Explain potential source controlled rectifier exciter system with diagram. **07**

OR

- Q.4** (a) Explain energy conversion in electromechanical system. **07**
(b) Develop dynamic model of synchronous machine with field circuit and two equivalent damper windings on q-axis (Model 2.2). Develop stator equations and draw its equivalent circuit. **07**

- Q.5** (a) A single machine system connected with infinite bus through resistance R_e and reactance X_e . Derive expression for ΔV_d and ΔV_q using machine model 1.0 and neglecting armature resistance. **08**
(b) Using rotor mechanical equations of synchronous machine obtain Torque-angle loop. **06**

OR

- Q.5** (a) State assumption made in Multi machine system and develop simplified system model for the same. **08**
(b) Draw overall block diagram of SMIB consisting the rotor swing equations, flux decay and excitation system. Neglect the damping term(D) in the swing equations for convenience. **06**
