

Seat No.: \_\_\_\_\_

Enrolment No. \_\_\_\_\_

## GUJARAT TECHNOLOGICAL UNIVERSITY

M. E. II<sup>ND</sup> Semester Examination – June/July- 2011

Subject code: 1720703

Subject Name: Power System Dynamics & Control

Date: 27/06/2011

Time: 10:30 am – 01:00 pm

Total Marks: 70

### Instructions:

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.

**Q.1 (a)** State conditions for synchronizing alternator with infinite bus considering fixed mechanical power i/p. **07**

How alternator acts as condenser to control reactive power ?

**(b)** State basic assumptions made in steady state analysis of an alternator and derive open circuit voltage equation of it. **07**

**Q.2 (a)** Using Park transformation derive voltage equation of synchronous machine. Also state importance of Park transformation. **07**

**(b)** State all assumptions made to develop dynamic model of synchronous machine and derive its all equations and draw phasor diagram. **07**

**OR**

**(b)** From basic of energy consumption principle derive mechanical equation for alternator. **07**

**Q.3 (a)** Given a round-rotor generator with  $V_a = 1.0$ ,  $X_s = 1.6$ ,  $r = 0.004$  and  $I_a = 1 \angle -60^\circ$ . Find  $E_a$ , draw a phasor diagram. **06**

**(b)** Derive equation for direct axis and quadrature axis voltages ( $V_d, V_q$ ) for non-synchronous operation of an alternator considering balanced terminal voltages with  $V_a(t) = \sqrt{2} |V| \cos(\omega_0 t + \angle V)$ . The rotation of generator is described by  $\theta = \omega_0 t + (\pi/2) + \delta$  **08**

**OR**

**Q.3 (a)** Draw and explain IEEE Type-1 excitation system. Also explain Excitation System Stabilizer (ESS) and Transient Gain Reduction (TGR) for excitation system modeling. **07**

**(b)** Draw and explain speed-governing system and model of speed-governing system for hydro turbines. **07**

**Q.4 (a)** Explain types of SVC. Where it is used ? **07**

**(b)** Classify the system load. Also state various mathematical model to represent system load. **07**

**OR**

**Q.4 (a)** Prove that, if the armature flux linkages components, with respect to a synchronously rotating reference frame are constants, then the transformer emf terms and terms introduced by the variations in rotor speed cancel each other. **07**

**(b)** Develop dynamic model of synchronous machine with field circuit and two equivalent damper windings on q-axis (Model 2.2). Develop all equations of stator and rotor and draw its equivalent circuit. **07**

- Q.5** (a) Carry out small signal analysis of excitation system of synchronous machine connects to infinite bus through transmission line. Also draw its block-diagram. **08**
- (b) Write short-note on Hopf Bifurcation. **06**
- OR**
- Q.5** (a) State assumption made in Multi machine system and develop simplified system model for the same. **08**
- (b) Explain line modeling by D-Q transformation using  $\alpha$ - $\beta$  variables. **06**

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